# Pradeep M

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# EDUCATION

# Bachelor of Engineering in Mechatronics Engineering (CGPA: 8.5/10)

Kumaraguru College of Technology, Coimbatore, India.

- Major Courses: C and Python Programming, Industrial Electronics and Drives, Control Engineering, Mobile Robotics, Design of Machine Elements, Computer Aided Design, Additive Manufacturing.

# **Higher secondary education**

Sengunthar Higher Secondary School.

• Stream: Computer Science

# WORK EXPERIENCE

#### Volar Alta, India.

Product Development Intern

- Design and Develop an dispatch payload system for UAVs
- Worked on Design, analysis, fabrication, and testing of the container.
- Worked in Embedded Systems and 3-D Printing.

# Forge Accelerator, Coimbatore, India.

Graduate Innovation Engineer

- We work as a team with students from different engineering streams, towards designing, developing and testing an innovative tech-enabled solution to solve a real-world problem sponsored by the industry.
- We innovate and design solutions by setting and achieving metrics for customer development & discovery, value-proposition validation

# **Mechathon Engineering Private Limited**

Product Design Intern

- Design, Assembly and 2D drafting of multi-plunger positive displacement pump
- Geometric Dimension & Tolerance and DFMA

# TECHNICAL SKILLS

#### Languages: Python, C++, C

**Tools/Frameworks**: ROS, OpenCV, MATLAB, Simulink, Fusion 360, Solid works, Ansys Basics, Labview ,Codesys [PLC Automation] **Others**: 3D Printing, Soldering, Prototyping , DevBoard [Jetson Nano, Arduino, Raspberry Pi 4, Node MCU ]

# PERSONAL PROJECTS

# AMR in Medical Logistics | Link

- Worked towards developing, simulating & testing the wheeled robot and perform agile movements.
- Mapping & ROS Navigation stack for wheeled robots.
- Designed and developed hardware for the entire mobile robot

#### Contactless and Optimized Cleaning for Urinals | Link

- Designed spreader using CAD with more than 6 different models based on materials usage.
- Performed analysis using Ansys for all the model and generated results based on the flow rate for each model.

# 3D Printed Prosthetic Arm Controlled using Electro Myro Sensor and Arduino Uno | Link

- Designed the Prosthetic Arm in CAD and performed analysis in joints, mechanism, and analysis of different static loads.
- Analyzing the movement of the robot under various circumstances and programming a servo with Arduino.
- Laser cutting and 3D printing were used to fabricate the design.

# **ACHIEVEMENTS**

- VISAI Project Competition-Vel Tech Mar 2021 Our team secured 1st in the project competition under the domain Clean water and Sanitization.
- Ingenious 2021 ISA VIT PUNE May 2021 Our team is the finalists in the Competition. We did a project titled.
  "Zeal Bot"



2017-2019

Oct 2021 – Feb 2022

Aug 2021 – Jan 2022

Jun 2021 – Aug 2021

Dec 2019

# Aug 2019-Present

# Oct 2020

Jun 2022

- 3D Model Creation with Autodesk Fusion 360 <u>Coursera</u>
- IoT (Internet of Things) Wireless & Cloud Computing Emerging Technologies Coursera
- Crash Course on Python <u>Coursera</u>
- Git and GitHub <u>Coursera</u>
- ROS SLAM Navigation Stack and Custom Robot Udemy
- Open CV- TDS <u>Robotics and Automation Forum</u>